Code: EC8T2D

## IV B.Tech-II Semester-Regular/Supplementary ExaminationsMarch 2020

## GLOBAL POSITIONING SYSTEM (ELECTRONICS AND COMMUNICATION ENGINEERING)

Duration: 3 hours
Max. Marks: 70
PART - A

Answer all the questions. All questions carry equal marks $11 \mathrm{x} 2=22 \mathrm{M}$
1.
a) Define Trilateration.
b) Define anti spoofing capability of GPS.
c) What is IOC and FOC?
d) List the GPS orbital parameters.
e) What are the two kinds of coded information in GPS receiver?
f) What is PRN code?
g) Classify the GPS errors.
h) What is multipath effect?
i) What is relative positioning in GPS data processing?
j) State the differences between equivalent and nonequivalent algorithms.
k) List the software development tools in GPS system.

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## PART - B

Answer any $\boldsymbol{T H R E E}$ questions. All questions carry equal marks.

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3 \times 16=48 \mathrm{M}
$$

2. a) Explain in detail about GPS functional segments. 8 M
b) Compare the characteristics of GPS and GALILEO Satellites.
3. a) What are the various GPS formats and explain about RINEX format.
b) Briefly explain how many satellites are required to compute receiver position in 2D and 3D Planes with the help of diagrams.
4. a) Explain about multipath errors and satellite clock errors.
b) Write short notes on ionospheric and tropospheric delay.
5. a) Discuss briefly about steps in the preparation of GPS data processing.
b) Explain kalman filtering using velocity information for GPS data processing.
6. a) Discuss functional library and data platform for GPS software development.
b) Explain the concept of flight state monitoring for GPS system.

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