Code: EC8T2D

IV B.Tech-II Semester–Regular/Supplementary Examinations– March 2020

GLOBAL POSITIONING SYSTEM (ELECTRONICS AND COMMUNICATION ENGINEERING)

Duration: 3 hours Max. Marks: 70

PART - A

Answer *all* the questions. All questions carry equal marks

11x 2 = 22 M

1.

- a) Define Trilateration.
- b) Define anti spoofing capability of GPS.
- c) What is IOC and FOC?
- d) List the GPS orbital parameters.
- e) What are the two kinds of coded information in GPS receiver?
- f) What is PRN code?
- g) Classify the GPS errors.
- h) What is multipath effect?
- i) What is relative positioning in GPS data processing?
- j) State the differences between equivalent and nonequivalent algorithms.
- k) List the software development tools in GPS system.

PART – B

Answer any <i>THREE</i> questions. All questions carry equal matrix $3 \times 16 = 4$		
		M
b) Compare the characteristics of GPS and GALILEO Satellites.	8	M
3. a) What are the various GPS formats and explain about RINEX format.	8	M
b) Briefly explain how many satellites are required to compute receiver position in 2D and 3D Planes with the help of diagrams.		M
4. a) Explain about multipath errors and satellite clock errors.	8	M
b) Write short notes on ionospheric and tropospheric delay		M
5. a) Discuss briefly about steps in the preparation of GPS da processing.	_	a M
b) Explain kalman filtering using velocity information for GPS data processing.	_	M
6. a) Discuss functional library and data platform for GPS software development.	8	M
b) Explain the concept of flight state monitoring for GPS system.	8	M